









- Dashboard
- Map
- IMU
- Drive
- Control
- Monitor
- Setting

Vehicle Info

Vehicle ID: 1
 Speed: 0 km/h
 Target Speed: 0 km/h
 State:



Steering Position ●

Controller Steering Position ●

Controller Accel

Controller Brake

NORMAL

PROGRAM

RIZO

DEAR V-

CPFL / Autoware

Unwatch 338 Unstar 2,397 Fork 1,101

Code Issues 165 Pull requests 42 Projects 1 Wiki Insights Settings

Open-Source To Self-Driving. <https://www.autoware.ai/>

Edit

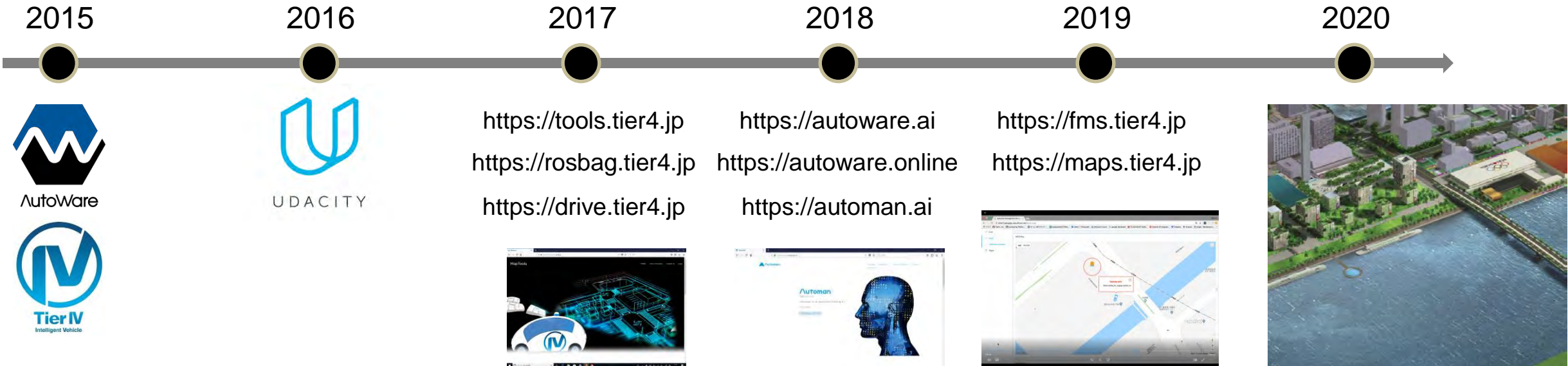
autoware autonomous-vehicles ros 3d-map detection planner calibration Manage topics

3,129 commits 124 branches 17 releases 59 contributors BSD-3-Clause

Branch: master New pull request Create new file Upload files Find file Clone or download

amc-nu [fix] Updated <code>ssd</code> readme (#1614)	Latest commit <code>c2ba68b</code> 7 days ago
<code>docker</code> [Feature] Cross compile for NVIDIA DriveWorks (#1447)	2 months ago
<code>docs</code> [Hotfix] Revise README.md (#1326)	4 months ago
<code>ros</code> [fix] Updated <code>ssd</code> readme (#1614)	7 days ago
<code>ui</code> Merge pull request #1173 from CPFL/feature/remote_monitor	7 months ago
<code>vehicle</code> Ignore when mode=-1	2 years ago
<code>.gitignore</code> fix unnecessary change	5 months ago
<code>.gitmodules</code> [fix] Pin <code>platform_automation_msgs</code> submodule (#1420)	3 months ago
<code>.travis.yml</code> [Fix] Clean up Build-Docker for each environments (#1433)	2 months ago
<code>AUTHORS</code> Add conference paepR information	6 months ago
<code>LICENSE</code> Initial commit for public release	3 years ago

Democratization of Intelligent Vehicles



Be Disruptive. Be Creative.